

## EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	229	robot near hand same (orientation orient)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2008/04/25 15:11
L2	0	robot near hand same (plurality multiple ) near (orientation orient)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2008/04/25 15:12
S1	3	(("6597971") or ("4402053") or ("4613269")).PN.	US-PGPUB; USPAT; USOOR	OR	OFF	2007/07/27 08:17
S2	1	("2004186624").PN.	US-PGPUB; USPAT; USOOR	OR	OFF	2007/07/27 08:18
S3	17052	(robot mechanical machine) and (arm limb appendage) and (hold grasp clutch grip clasp) and (proximal) and (distal) and (orientation bearing direction coordination position)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/07/27 12:31
S4	1161	(robot mechanical machine) and (arm limb appendage) and (hold grasp clutch grip clasp) and (proximal) and (distal) and (orientation bearing direction coordination position) same container	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/07/27 12:31
S5	610	(robot machine) and (arm limb appendage) and (hold grasp clutch grip clasp) and (proximal) and (distal) and (orientation bearing direction coordination position) same container	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/07/27 12:32
S6	110	(robot machine) and (arm limb appendage) and (hold grasp clutch grip clasp) and (proximal) and (distal) and (orientation bearing direction coordination position) and (visual ccd camera optical) same container	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/07/27 12:33

S7	12	(robot android machine) same (arm limb appendage) same (hold grasp clutch grip clasp) same (visual ccd camera optical) same (orientation bearing direction coordination position) same (container)	US_PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/07/27 12:34
S8	69	(robot android machine) same (arm limb appendage) same (hold grasp clutch grip clasp) same (visual ccd camera optical) same (orientation bearing direction coordination position) same (container)	US_PGPUB; USPAT; USOOR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/07/27 12:34
S9	1076	robot near (hand grip) same (hold orientation)	US_PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2008/04/18 12:08
S10	31	robot near (hand grip) same (hold grasp ) same orientation	US_PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2008/04/18 12:09
S11	51	("4658428"   "5220619"). PN. OR ("5471541"). URPN.	US_PGPUB; USPAT; USOOR	OR	ON	2008/04/18 15:02
S12	64	"4402053"	US_PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2008/04/18 15:03
S13	46	robot near (hand grip gripper) same (hold grasp ) same orientation	US_PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2008/04/18 15:40
S14	1985	(700/245).CCLS.	US_PGPUB; USPAT; USOOR	OR	OFF	2008/04/18 15:41
S15	596	(700/259).CCLS.	US_PGPUB; USPAT; USOOR	OR	OFF	2008/04/18 15:41
S16	1002	taking near out near apparatus	US_PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2008/04/21 08:12
S17	451	taking near out and robot near arm	US_PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2008/04/21 08:12
S18	127	taking near out same robot near arm	US_PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2008/04/21 08:53
S19	384	(offset off-set off adj set) same (robot near arm)	US_PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2008/04/21 10:57

S20	217	(offset off-set off adj set) same (robot near arm) same (orientation pose position)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2008/04/21 10:57
S21	1	("4402053").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/04/22 09:31

4/ 25/ 2008 5:20:23 PM

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